Hyperelliptic solutions of modified Korteweg-de Vries equation of genus $g$ : essentials of the Miura transformation

This article has been downloaded from IOPscience. Please scroll down to see the full text article. 2002 J. Phys. A: Math. Gen. 354321
(http://iopscience.iop.org/0305-4470/35/19/312)
View the table of contents for this issue, or go to the journal homepage for more

Download details:
IP Address: 171.66.16.106
The article was downloaded on 02/06/2010 at 10:04

Please note that terms and conditions apply.

# Hyperelliptic solutions of modified Korteweg-de Vries equation of genus $g$ : essentials of the Miura transformation 

Shigeki Matsutani<br>8-21-1 Higashi-Linkan, Sagamihara 228-0811, Japan<br>E-mail: RXB01142@nifty.ne.jp

Received 12 November 2001, in final form 8 March 2002
Published 3 May 2002
Online at stacks.iop.org/JPhysA/35/4321


#### Abstract

Explicit hyperelliptic solutions of the modified Korteweg-de Vries equations without any ambiguous parameters were constructed in terms of only the hyperelliptic al-functions over the non-degenerate hyperelliptic curve $y^{2}=$ $f(x)$ of arbitrary genus $g$. In the derivation, any $\theta$-functions or BakerAkhiezer functions were not essentially used. Then the Miura transformation naturally appears as the connection between the hyperelliptic $\wp$-functions and hyperelliptic al-functions.


PACS numbers: $02.30 . \mathrm{Gp}, 02.30 . \mathrm{Dk}, 02.30 . \mathrm{Ik}, 02.30 . \mathrm{Jr}, 05.45 . \mathrm{Yv}, 43.25 . \mathrm{Rq}$
Mathematics Subject Classification: 37K20, 35Q53, 14H45, 14H70

## 1. Introduction

It might not be an exaggeration to say that the discovery of the Miura transformation opened the modern soliton theory [GGKM]. Using this, the inverse scattering method was discovered and developed [L]. In such developments of the theory, there appeared several algebraic solutions of integrable nonlinear differential equations in the 1970s [ Kr ] (references in [BBEIM,MT,TD]). These solutions were obtained by arguments on the behaviours of algebraic or meromorphic functions around infinite points of corresponding algebraic curves. Their arguments are based on certain existence theorems of holomorphic functions and the theorem of identity of analytic functions. They played very important roles and contributed to the developments of the soliton theories in the 1980s. They are especially connected to the abstract theories of modern mathematics, which are, now, called infinite-dimensional analysis [DKJM, SN, SS]. Thus, needless to say, they also have important meanings.

However their solutions are not, sometimes, enough to have effects on some concrete computations of algebraic solutions, for example the cases in which one wishes to determine
coefficients of higher degrees of Laurent or Taylor expansions of the solutions and in which one wishes to draw a graph of solutions without computation of transcendental equations. Recently theories of hyperelliptic functions which were discovered in the 19th century [ Ba , $\mathrm{Ba} 2, \mathrm{Ba} 3, \mathrm{~K} 11]$ have been re-evaluated in various fields [BEL1, BEL2, BEL3, CEEK, EE, EEK, EEL,EEP, G, Ma2, Ma3, Ma4, Ma5, N, Ô1, Ô2]. One purpose of the re-evaluations seems to be to reconstruct and to refine the modern soliton theory and algebraic geometry.

The theories of the 19th century are very concrete. First they chose a hyperelliptic curve. After fixing the curve, they considered the meromorphic functions over it. In the 19th century, the study of the hyperelliptic functions was very important as a generalization of elliptic functions, and was performed by Weierstrass, Klein, Jacobi and so on [D, K12]. Surprisingly, even in the 19th century, there appeared most of the tools and objects in soliton theories. In fact, Baker found the Korteweg-de Vries (KdV) hierarchy and Kadomtsev-Petviashvili (KP) equations around 1898 in terms of bilinear operators, Paffians, symmetric functions and so on [Ba3, Ma3].

As we enter the 21st century now, we can look around both of them. It is very interesting to compare the theory of soliton equations at the end of the last century with that of hyperelliptic functions in the 19th century. Both have merits and demerits. When one wishes for concrete expressions, the theories of the 19th century are very convenient. However, if one wishes to use the framework of infinite-dimensional analysis, the older theories might be useless.

This paper is on the hyperelliptic solutions of the modified KdV equation (MKdV) related to hyperelliptic curves with higher genus by employing the fashion in the 19th century. In the previous report [Ma2], I constructed those of genus one and two associated with loop solitons and the statistical mechanics of elastic rods. As mentioned in [Ma1], when one considers the statistical mechanics (or quantization) of ideal thin elastic rods in a plane, for example ideal polymers in a plane, the MKdV equation naturally appears and algebraic solutions (hyperelliptic solutions, or quasi-periodic solutions) of the MKdV equation have physical meaning. It is worthwhile to note that it is not trivial that the algebraic solution with higher genus is related to a physical system in low-energy physics; even for many cases which are known as physical models of solitons, quasi-periodic solutions with higher genus are often out of the range of the approximations on the models. Thus it should be noted that our investigation of the algebraic solutions of the MKdV equation is directly related to the physical system of statistical mechanics of polymers in a plane [Ma1,Z].

This paper is one of two reports as the extensions of [Ma2] to arbitrary genus. In another one [Ma5] we give a geometrical investigation of the loop solitons using the result of this paper, whereas in this paper we shall concentrate our attention on the analytic arguments on the algebraic solutions of the MKdV equations. In this paper, using only the Weierstrass al-function [W], [Ba2, p 340], we shall construct the hyperelliptic solutions of the MKdV equation in theorem 3.2. In the construction, we shall not essentially use any $\theta$-functions or Baker-Akhiezer functions though the algebro-geometric solutions in terms of Baker-Akhiezer functions were obtained by Gesztesy and Holden recently [GH1]; they did not mention a connection between their solutions and the al-function. Our solutions are explicitly constructed without ambiguous parameters for arbitrary hyperelliptic curves and our construction might be, I believe, simpler than that in terms of Baker-Akhiezer functions. In the construction, we translate the differential operators in the Jacobian into those in the curve itself and evaluate the related terms by using residual computations and symmetries. As the Weierstrass al-function should be regarded as a generalization of the Jacobi elliptic functions and in a calculus of Jacobi elliptic functions, we do not usually need $\theta$-functions; our construction is more natural.

In the construction of the hyperelliptic solutions of the MKdV equation, we compare the hyperelliptic $\wp$ and al-functions. As the hyperelliptic $\wp$ functions are connected with the
finite-type solutions of the KdV equation [BEL1, BEL2, Ma3], we can investigate the Miura transformation between finite-type solutions of the KdV equations and MKdV equations. In remark 3.3 and section 4, we show that the Miura transformation for the finite-type solutions is also natural from several viewpoints. Here we should remark that the comparison is essentially the same as Baker's arguments in [Ba3]; there he found the KdV hierarchy and KP equation as relations among the $\wp$ functions [Ba3, Ma3]. Further, we note that, even though they did not mention it, Eilbeck, Enolskii and Kostov also found a similar relation between $\wp$ and al in their computations of the vector nonlinear Schrödinger equation [EEK].

Due to [GGKM], any solution of the KdV equation can be regarded as a potential in a one-dimensional Schrödinger equation whose spectrum is preserved for the time development of the solutions. From the spectral theory [BBEIM, MT], the spectrum is determined by a characteristic relation over the complex number, which is identified with a 'hyperelliptic curve' with a certain genus including infinite genus. For the finite case, the solutions of the KdV equation are given as finite-type solutions associated with the hyperelliptic curve. However in general the genus of the characteristic relation is not finite. Even if the characteristic relation has infinite genus, we can essentially deal with the solution of the KdV equation as in the case of finite genus by taking the limit of the genus to infinity; though there are some obstacles, we can overcome them [MT]. Thus we could recognize that our remarks in sections 3 and 4 for the finite-genus case exhibit essentials of the Miura transformation. Though Gesztesy and Holden [GH2] also considered the Miura transformation from the viewpoint of algebrogeometrical computations of the MKdV equation, our viewpoint on the remarks differs from theirs. Our remarks give another aspect of the Miura transformation.

## 2. Differentials of a hyperelliptic curve

In this section, we shall give the conventions which express the hyperelliptic functions in this paper. As there is a good self-contained paper on theories of hyperelliptic sigma functions [BEL2] besides [ $\mathrm{Ba} 1, \mathrm{Ba} 2, \mathrm{Ba} 3$ ], we shall give them without explanations and proofs.

We denote the set of complex numbers by $\mathbb{C}$ and the set of integers by $\mathbb{Z}$.
Convention 2.1. We deal with a hyperelliptic curve $C_{g}$ of genus $g(g>0)$ given by the affine equation
$y^{2}=f(x)=\lambda_{2 g+1} x^{2 g+1}+\lambda_{2 g} x^{2 g}+\cdots+\lambda_{2} x^{2}+\lambda_{1} x+\lambda_{0}=P(x) Q(x)$,
where $\lambda_{2 g+1} \equiv 1$ and the $\lambda_{j}$ are complex numbers. We use the expressions

$$
\begin{align*}
& f(x)=\left(x-b_{1}\right)\left(x-b_{2}\right) \cdots\left(x-b_{2 g}\right)\left(x-b_{2 g+1}\right), \\
& Q(x)=\left(x-c_{1}\right)\left(x-c_{2}\right) \cdots\left(x-c_{g}\right)(x-c),  \tag{2.2}\\
& P(x)=\left(x-a_{1}\right)\left(x-a_{2}\right) \cdots\left(x-a_{g}\right),
\end{align*}
$$

where the $a_{j}, b_{j}, c_{j}$ and $c$ are complex values and $b_{2 g+2}=\infty$.
Proposition 2.2. There exist several symmetries which express the same curve $C_{g}$.
(1) Translational symmetry: for $\alpha_{0} \in \mathbb{C},(x, y) \rightarrow\left(x+\alpha_{0}, y\right)$, with $b_{j} \rightarrow b_{j}+\alpha_{0}$.
(2) Dilatation symmetry: for $\alpha_{1} \in \mathbb{C},(x, y) \rightarrow\left(\alpha_{0} x, \alpha_{0}^{2 g+1} y\right)$, with $b_{j} \rightarrow \alpha_{0} b_{j}$.
(3) Inversion symmetry: for fixing $b_{i},(x, y) \rightarrow\left(1 /\left(x-b_{i}\right), y \prod_{j \neq i} \sqrt{b_{i}-b_{j}} /\right.$ $\left.\left(x-b_{i}\right)^{(2 g+1) / 2}\right)$ with $b_{j} \rightarrow 1 /\left(b_{j}-b_{i}\right)$.

Definition 2.3 (see [Ba1, Ba2, BEL2, Ô1]). For a point $\left(x_{i}, y_{i}\right) \in C_{g}$, we define the following quantities:
(1) Let us denote the homology of a hyperelliptic curve $C_{g}$ by

$$
\begin{equation*}
\mathrm{H}_{1}\left(C_{g}, \mathbb{Z}\right)=\bigoplus_{j=1}^{g} \mathbb{Z} \alpha_{j} \oplus \bigoplus_{j=1}^{g} \mathbb{Z} \beta_{j} \tag{2.3}
\end{equation*}
$$

where these intersections are given as $\left[\alpha_{i}, \alpha_{j}\right]=0,\left[\beta_{i}, \beta_{j}\right]=0$ and $\left[\alpha_{i}, \beta_{j}\right]=\delta_{i, j}$.
(2) The un-normalized differentials of the first kind are defined by

$$
\begin{equation*}
\mathrm{d} u_{1}^{(i)}:=\frac{\mathrm{d} x_{i}}{2 y_{i}}, \quad \mathrm{~d} u_{2}^{(i)}:=\frac{x_{i} \mathrm{~d} x_{i}}{2 y_{i}}, \ldots, \quad \mathrm{~d} u_{g}^{(i)}:=\frac{x_{i}^{g-1} \mathrm{~d} x_{i}}{2 y_{i}} \tag{2.4}
\end{equation*}
$$

(3) The un-normalized complete hyperelliptic integrals of the first kind are defined by

$$
\omega^{\prime}:=\left[\left(\int_{\alpha_{j}} \mathrm{~d} u_{i}^{(a)}\right)_{i j}\right], \quad \omega^{\prime \prime}:=\left[\left(\int_{\beta_{j}} \mathrm{~d} u_{i}^{(a)}\right)_{i j}\right], \quad \omega:=\left[\begin{array}{c}
\boldsymbol{\omega}^{\prime}  \tag{2.5}\\
\omega^{\prime \prime}
\end{array}\right] .
$$

(4) The normalized complete hyperelliptic integrals of the first kind are given by

$$
\tau:=\omega^{\prime-1} \omega^{\prime \prime}, \quad \hat{\omega}:=\left[\begin{array}{c}
1_{g}  \tag{2.6}\\
\tau
\end{array}\right] .
$$

(5) The un-normalized differentials of the second kind are defined by

$$
\begin{align*}
& \mathrm{d} \tilde{u}_{1}^{(i)}:=\frac{x_{i}^{g} \mathrm{~d} x_{i}}{2 y_{i}}, \quad \mathrm{~d} \tilde{u}_{2}^{(i)}:=\frac{x_{i}^{g+1} \mathrm{~d} x_{i}}{2 y_{i}}, \ldots, \quad \mathrm{~d} \tilde{u}_{g}^{(i)}:=\frac{x_{i}^{2 g-1} \mathrm{~d} x_{i}}{2 y_{i}},  \tag{2.7}\\
& \quad \text { and } \mathrm{d} \boldsymbol{r}^{(i)}:=\left(\mathrm{d} r_{1}^{(i)}, \mathrm{d} r_{2}^{(i)}, \ldots, \mathrm{d} r_{g}^{(i)}\right), \\
& \left(\mathrm{d} \boldsymbol{r}^{(i)}\right):=\Lambda\binom{\mathrm{d} \boldsymbol{u}^{(i)}}{\mathrm{d} \tilde{\boldsymbol{u}}^{(i)}}, \tag{2.8}
\end{align*}
$$

where $\Lambda$ is a $2 g \times g$ matrix defined by

$$
\Lambda=\left(\begin{array}{cccccccc}
0 & \lambda_{3} & 2 \lambda_{4} & 3 \lambda_{5} & \cdots & (g-1) \lambda_{g+1} & g \lambda_{g+2} & (g+1) \lambda_{g+3} \\
& 0 & \lambda_{5} & 2 \lambda_{6} & \cdots & (g-2) \lambda_{g+2} & (g-1) \lambda_{g+3} & g \lambda_{g+4} \\
& & 0 & \lambda_{7} & \cdots & (g-3) \lambda_{g+3} & (g-2) \lambda_{g+4} & (g-1) \lambda_{g+5} \\
& & & & \ddots & \vdots & \vdots & \vdots  \tag{2.9}\\
& & 0 & & & \lambda_{2 g-2} & 2 \lambda_{2 g-1} & 3 \lambda_{2 g+1} \\
& & & & 0 & \lambda_{2 g+1} & 0 \\
& \cdots & (2 g-3) \lambda_{2 g-1} & (2 g-2) \lambda_{2 g} & (2 g-1) \lambda_{2 g+1} \\
& \cdots & (2 g-4) \lambda_{2 g} & (2 g-3) \lambda_{2 g+1} & 0 \\
& \cdots & (2 g-5) \lambda_{2 g+1} & 0 & \\
& \cdots & 0 & &
\end{array}\right) .
$$

(6) The complete hyperelliptic integral matrices of the second kind are defined by

$$
\begin{equation*}
\eta^{\prime}:=\left[\left(\int_{\alpha_{j}} \mathrm{~d} r_{i}^{(a)}\right)_{i j}\right], \quad \eta^{\prime \prime}:=\left[\left(\int_{\beta_{j}} \mathrm{~d} r_{i}^{(a)}\right)_{i j}\right] . \tag{2.10}
\end{equation*}
$$

(7) By defining the Abel map for the gth symmetric product of the curve $C_{g}$,

$$
\begin{align*}
& u \equiv\left(u_{1}, \ldots, u_{g}\right): \operatorname{Sym}^{g}\left(C_{g}\right) \longrightarrow \mathbb{C}^{g}, \\
& \left(u_{k}\left(\left(x_{1}, y_{1}\right), \ldots,\left(x_{g}, y_{g}\right)\right):=\sum_{i=1}^{g} \int_{\infty}^{\left(x_{i}, y_{i}\right)} \mathrm{d} u_{k}^{(i)}\right), \tag{2.11}
\end{align*}
$$

the Jacobi varieties $\mathcal{J}_{g}$ are defined as a complex torus,

$$
\begin{equation*}
\mathcal{J}_{g}:=\mathbb{C}^{g} / \boldsymbol{\Lambda} \tag{2.12}
\end{equation*}
$$

Here $\boldsymbol{\Lambda}$ is a g-dimensional lattice generated by $\omega$.

Definition 2.4. The coordinate in $\mathbb{C}^{g}$ for points $\left(x_{i}, y_{i}\right)_{i=1, \ldots, g}$ of the curve $y^{2}=f(x)$ is given by

$$
\begin{equation*}
u_{j}:=\sum_{i=1}^{g} \int_{\infty}^{\left(x_{i}, y_{i}\right)} \mathrm{d} u_{j}^{(i)} . \tag{2.13}
\end{equation*}
$$

(1) The hyperelliptic $\sigma$ function, which is a holomorphic function over $u \in \mathbb{C}^{g}$, is defined by [Ba2, p 336, p 350], [Kll, BEL2]

$$
\sigma(u)=\sigma\left(u ; C_{g}\right):=\gamma \exp \left(-\frac{1}{2}^{t} u \boldsymbol{\eta}^{\prime} \boldsymbol{\omega}^{\prime-1} u\right) \vartheta\left[\begin{array}{c}
\delta^{\prime \prime}  \tag{2.14}\\
\delta^{\prime}
\end{array}\right]\left(\boldsymbol{\omega}^{\prime-1} u ; \boldsymbol{\tau}\right)
$$

where $\gamma$ is a certain constant factor,

$$
\vartheta\left[\begin{array}{l}
a  \tag{2.15}\\
b
\end{array}\right](z ; \boldsymbol{\tau}):=\sum_{n \in \mathbb{Z}^{g}} \exp \left[2 \pi \sqrt{-1}\left\{\frac{1}{2}^{t}(n+a) \tau(n+a)+{ }^{t}(n+a)(z+b)\right\}\right]
$$

for $g$-dimensional vectors $a$ and $b$ and

$$
\delta^{\prime}:=t\left[\begin{array}{llll}
\frac{g}{2} & \frac{g-1}{2} & \cdots & \frac{1}{2} \tag{2.16}
\end{array}\right], \quad \delta^{\prime \prime}:={ }^{t}\left[\frac{1}{2} \cdots \frac{1}{2}\right] .
$$

(2) The hyperelliptic $\wp$-function is defined by [Ba2, p 370], [Ba1, BEL2]

$$
\begin{equation*}
\wp_{i j}(u):=-\frac{\partial^{2}}{\partial u_{i} \partial u_{j}} \log \sigma(u) . \tag{2.17}
\end{equation*}
$$

(3) The hyperelliptic al-function is defined by [Ba2, p 340], [W]

$$
\begin{equation*}
\mathrm{al}_{r}(u):=\gamma^{\prime} \sqrt{F\left(b_{r}\right)}, \tag{2.18}
\end{equation*}
$$

where $\gamma^{\prime}$ is a certain constant factor,

$$
\begin{equation*}
F(x):=\left(x-x_{1}\right) \cdots\left(x-x_{g}\right)=\gamma_{g} x^{g}+\gamma_{g-1} x^{g-1}+\cdots+\gamma_{0}, \tag{2.19}
\end{equation*}
$$

$\gamma_{g} \equiv 1$ and $\gamma_{i}$ are elementary symmetric functions of $x_{i}$.
Here we note that in [Ba2] Baker used another notation $\mathrm{cl}_{r}$ for a point $b_{r} \in\left\{a_{j}\right\}$ of (2.2) instead of $\mathrm{al}_{r}$, but I shall follow the original definition of Weierstrass [W].

## Proposition 2.5.

(1) $\wp_{g i}(i=1, \ldots, g)$ is the elementary symmetric functions of $\left\{x_{1}, x_{2}, \ldots, x_{g}\right\}$, i.e. for $\left(x_{1}, \ldots, x_{g}\right) \in \operatorname{Sym}\left(C^{g}\right)$ [Ba1, BEL2],

$$
\begin{equation*}
F(x)=x^{g}-\sum_{i=1}^{g} \wp_{g i} x^{i-1} \tag{2.20}
\end{equation*}
$$

(2) $U:=\left(2 \wp_{g g}+\lambda_{2 g} / 6\right)$ obeys the KdV equations [BEL2, p 52-53],

$$
\begin{equation*}
4 \frac{\partial U}{\partial u_{g-1}}+6 U \frac{\partial U}{\partial u_{g}}+\frac{\partial^{3} U}{\partial u_{g}}=0 \tag{2.21}
\end{equation*}
$$

(3) Introducing the half-period $\omega_{r}:=\int_{\infty}^{b_{r}} \mathrm{~d} u^{(a)}$, we have

$$
\begin{equation*}
\mathrm{al}_{r}(u)=\gamma_{r}^{\prime \prime} \frac{\exp \left(-u \boldsymbol{\eta}^{\prime} \boldsymbol{\omega}^{\prime-1} \omega_{r}\right) \sigma\left(u+\omega_{r}\right)}{\sigma(u)}, \tag{2.22}
\end{equation*}
$$

where $\gamma_{r}^{\prime \prime}$ is a certain constant [Ba2, p 340].

## Definition 2.6.

(1) A polynomial associated with $F(x)$ is defined by

$$
\begin{equation*}
\pi_{i}(x):=\frac{F(x)}{x-x_{i}}=\chi_{i, g-1} x^{g-1}+\chi_{i, g-2} x^{g-2}+\cdots+\chi_{i, 1} x+\chi_{i, 0}, \tag{2.23}
\end{equation*}
$$

where $\chi_{i, g-1} \equiv 1, \chi_{i, g-2}=\left(x_{1}+\cdots+x_{g}\right)-x_{i}$, and so on.
(2) We shall introduce $g \times g$ matrices,

$$
\begin{align*}
W & :=\left(\begin{array}{cccc}
\chi_{1,0} & \chi_{1,1} & \cdots & \chi_{1, g-1} \\
\chi_{2,0} & \chi_{2,1} & \cdots & \chi_{2, g-1} \\
\vdots & \vdots & \ddots & \vdots \\
\chi_{g, 0} & \chi_{g, 1} & \cdots & \chi_{g, g-1}
\end{array}\right), \quad \mathcal{Y}:=\left(\begin{array}{llll}
y_{1} & & & \\
& y_{2} & & \\
& & \ddots & \\
& & & y_{g}
\end{array}\right),  \tag{2.24}\\
\mathcal{F}^{\prime} & :=\left(\begin{array}{ccccc}
F^{\prime}\left(x_{1}\right) & & & \\
& F^{\prime}\left(x_{2}\right) & & \\
& & & \ddots & \\
& & & & F^{\prime}\left(x_{g}\right)
\end{array}\right),
\end{align*}
$$

where $F^{\prime}(x):=\mathrm{d} F(x) / \mathrm{d} x$.

## Lemma 2.7.

(1) The inverse matrix of $W$ is given by $W^{-1}=\mathcal{F}^{-1} V$, where $V$ is the Vandermond matrix,

$$
V:=\left(\begin{array}{cccc}
1 & 1 & \cdots & 1  \tag{2.25}\\
x_{1} & x_{2} & \cdots & x_{g} \\
x_{1}^{2} & x_{2}^{2} & \cdots & x_{g}^{2} \\
\vdots & \vdots & & \vdots \\
x_{1}^{g-1} & x_{2}^{g-1} & \cdots & x_{g}^{g-1}
\end{array}\right) .
$$

(2) By letting $\partial_{u_{i}}:=\partial / \partial u_{i}$ and $\partial_{x_{i}}:=\partial / \partial x_{i}$, we obtain

$$
\left(\begin{array}{c}
\partial_{u_{1}}  \tag{2.26}\\
\partial_{u_{2}} \\
\vdots \\
\partial_{u_{g}}
\end{array}\right)=2 \mathcal{Y} \mathcal{F}^{\prime-1}{ }^{t} W\left(\begin{array}{c}
\partial_{x_{1}} \\
\partial_{x_{2}} \\
\vdots \\
\partial_{x_{g}}
\end{array}\right) .
$$

Proof. (1) is obvious by direct substitution and uniqueness of an inverse matrix. We should pay attention to the fixed parameters in the partial differential in (2). $\frac{\partial}{\partial u_{i}}$ means $\left(\frac{\partial}{\partial u_{i}}\right)$ where indices are fixed parameters. Since

$$
\begin{equation*}
\mathrm{d} x_{i}=\sum_{j=1}^{g}\left(\frac{\partial x_{i}}{\partial u_{j}}\right)_{u_{1}, \ldots, u_{j-1}, u_{j+1}, \ldots, u_{g}} \mathrm{~d} u_{j}, \tag{2.27}
\end{equation*}
$$

we have

$$
\begin{equation*}
\left(\frac{\partial}{\partial u_{i}}\right)_{u_{1}, \ldots, u_{i-1}, u_{i+1}, \ldots, u_{g}}=\sum_{j=1}^{g}\left(\frac{\partial x_{j}}{\partial u_{i}}\right)_{u_{1}, \ldots, u_{i-1}, u_{i+1}, \ldots, u_{g}} \frac{\partial}{\partial x_{i}} . \tag{2.28}
\end{equation*}
$$

Comparing (2.27) with the definitions (2.4), (2.11) and (2.13), (2) is proved.

## 3. Hyperelliptic solutions of modified Korteweg-de Vries equation

In this section, we shall give hyperelliptic solutions of the MKdV equation and Miura transformation in terms of the theory of hyperelliptic functions developed in the 19th century.

First we shall define the MKdV equation.
Definition 3.1. The $M K d V$ equation is given by the form

$$
\begin{equation*}
\frac{\partial}{\partial t} q+6 q^{2} \frac{\partial}{\partial s} q+\frac{\partial^{3}}{\partial s^{3}} q=0 \tag{3.1}
\end{equation*}
$$

where $t$ and $s$ are real or complex numbers.
Then we shall give our main theorem of this paper as follows.

## Theorem 3.2.

(1) By letting

$$
\begin{equation*}
\mu^{(r)}=\frac{1}{2} \frac{\partial}{\partial u_{g}} \phi^{(r)}, \quad \phi^{(r)}(u):=\frac{1}{\sqrt{-1}} \log F\left(b_{r}\right) \tag{3.2}
\end{equation*}
$$

$\mu^{(r)}$ obeys the modified KdV equation,

$$
\begin{equation*}
\left(\frac{\partial}{\partial u_{g-1}}-\left(\lambda_{2 g}+b_{r}\right) \frac{\partial}{\partial u_{g}}\right) \mu^{(r)}-6 \mu^{(r)^{2}} \frac{\partial}{\partial u_{g}} \mu^{(r)}+\frac{\partial^{3}}{\partial u_{g}^{3}} \mu^{(r)}=0 . \tag{3.3}
\end{equation*}
$$

(2) We have the Miura relation,

$$
\begin{equation*}
2 \wp_{g g}+\lambda_{2 g}+b_{r}=\mu^{(r)^{2}}+\sqrt{-1} \frac{\partial}{\partial u_{g}} \mu^{(r)} \tag{3.4}
\end{equation*}
$$

Before proving the theorem, we shall remark on the meanings of our theorem.

## Remark 3.3.

(1) For arbitrary hyperelliptic curves, we can construct $\mu^{(r)}$ in (3.2) which obeys the MKdV equation in terms of the hyperelliptic al-function, $\mathrm{al}_{r}=\gamma^{\prime} \sqrt{F\left(b_{r}\right)}$. This means that we present all finite-type solutions of the MKdV equation which are expressed by meromorphic functions over hyperelliptic curves up to the symmetries of proposition 2.2. Due to (2.14) and (2.22), our solution is connected with that in [GH1].
(2) Using the Miura transformation, the theorem and our proof mean that we have another proof of proposition 2.5 (2) on the hyperelliptic solutions of the KdV equation beside [BBEIM, BEL1, BEL2].
(3) There is a map from $\operatorname{Sym}^{g}\left(C_{g}\right)$ to $\mathbb{C} P^{1}$

$$
\left\{\left(x_{1}, x_{2}, \ldots, x_{g}\right)\right\} \xrightarrow{u} \begin{gather*}
\mathcal{J}  \tag{3.5}\\
\\
\\
\\
\left\{x_{1}+\cdots+x_{g}\right\}
\end{gather*}
$$

and this characterizes the $\wp_{g g}$ function [BBEIM]. It is noted that we can regard this map as a global affine map between the affine spaces, $\operatorname{Sym}^{g}\left(C_{g}\right)$ and $\mathbb{C}$. The global translation and dilation $x_{i} \rightarrow a x_{i}+b$ for all $i(a, b \in \mathbb{C})$ makes $\wp_{g g} \rightarrow a \wp_{g g}+g b$ but the curve $C_{g}$ does not change due to proposition 2.2. This translation freedom should be one of the keys of the inverse scattering method [GGKM]. Further Miura transformation connects between objects which are invariant and variant for translation respectively. In fact for the translation, Weierstrass al-functions are invariant. This reminds us of a stabilizer in homogeneous space.

Further we remark that in the property of an infinite point, $\infty+a=\infty$, the invariance can be translated to an analysis at an infinite point. With the properties of the degenerate curve $y^{2}=P(x)^{2} x$ as mentioned in [Ma4], Miura transformation can be interpreted as Bäcklund transformation in a certain case.
(4) From the point of view of study of symmetric functions, $F(x)$ is a generator of the elementary symmetric functions, whereas from (3.9) the definition of $\mu^{(r)}$ in (3.2) resembles the generator of the power sum symmetric function [Mac]

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} x} \log F(x)=\frac{1}{x} \sum_{j=0}^{\infty}\left[\sum_{i=1}^{n} x_{i}^{j}\right] \frac{1}{x^{j}} \tag{3.6}
\end{equation*}
$$

(5) Due to the Miura transformation, the differential $\partial \mu^{(r)} / \partial u_{g}$ can be expressed by a polynomial of $\wp_{g g}$ and $\mu^{(r)}$. In other words, it connects categories of analysis and algebra. In fact, the Miura transformation can be translated into a language in the theory of a geometrical Dirac equation of a curve in a complex plane, or the Frenet-Serret relation [Ma5]. There the Miura transformation is interpreted as an integrability condition in the $\mathcal{D}$-module (see [ $\mathrm{Bj}, \mathrm{p} 12-13]$, [Ma5]).
(6) In [EEK], Eilbeck et al studied the vector nonlinear Schrödinger equations and obtained a formula ((3.8) in [EEK]) which is essentially the same as (3.4), even though they did not mention a relation between their formula and the Miura transformation.

Here we shall mention our plan to prove the theorem. First we shall prove the Miura relation (3.4). As the first step in its proof, we shall translate the operation of $\partial / \partial u_{g}$ into that of $\partial / \partial x_{i}$ and compute (3.2). Secondly we shall evaluate the obtained terms by using the symmetries of summation and residual computation over the curve. Then we obtain the Miura relation (3.4). Next, we shall investigate the right-hand side in an integration version of (3.3). If we show that $\phi^{(r)}$ in (3.2) obeys

$$
\begin{equation*}
4\left(\frac{\partial}{\partial u_{g-1}}-\left(\lambda_{2 g}+b_{r}\right) \frac{\partial}{\partial u_{g}}\right) \phi^{(r)}+\frac{1}{2}\left(\frac{\partial}{\partial u_{g}} \phi^{(r)}\right)^{3}+\frac{\partial^{3}}{\partial u_{g}^{3}} \phi^{(r)}=0, \tag{3.7}
\end{equation*}
$$

we have a solution of (3.3) by differentiating (3.7) in $u_{g}$ again. In the derivation, we shall use the Miura relation and correspondences between $\partial / \partial u_{g-1}$ and the $\partial / \partial x_{i}$. We shall obtain (3.7) at (3.31).

Now let us prove the theorem. From (2.26), we shall express the $u$ by the affine coordinates $x_{i}$,

$$
\begin{equation*}
\frac{\partial}{\partial u_{g}}=\sum_{i=1}^{g} \frac{2 y_{i}}{F^{\prime}\left(x_{i}\right)} \frac{\partial}{\partial x_{i}}, \quad \frac{\partial}{\partial u_{g-1}}=\sum_{i=1}^{g} \frac{2 y_{i} \chi_{i, g-1}}{F^{\prime}\left(x_{i}\right)} \frac{\partial}{\partial x_{i}} . \tag{3.8}
\end{equation*}
$$

Hence we have
$\mu^{(r)} \equiv \frac{1}{2 \sqrt{-1}} \frac{\partial}{\partial u_{g}} \log F\left(b_{r}\right)=\frac{1}{\sqrt{-1}} \sum_{i=1}^{g} \frac{y_{i}}{F^{\prime}\left(x_{i}\right)\left(x_{i}-b_{r}\right)}=\frac{1}{\sqrt{-1}} \sum_{j=1}^{\infty} \sum_{i=1}^{g} \frac{y_{i}}{F^{\prime}\left(x_{i}\right) b_{r}} \frac{x_{i}^{j}}{b_{r}^{j}}$,
$\frac{\partial}{\partial u_{g-1}} \log F\left(b_{r}\right)=\sum_{i=1}^{g} \frac{2 y_{i} \chi_{i, g-1}}{F^{\prime}\left(x_{i}\right)\left(x_{i}-b_{r}\right)}$.
Roughly speaking, we wish to compute

$$
\begin{equation*}
\frac{1}{2} \frac{\partial^{2}}{\partial u_{g}^{2}} \log F\left(b_{r}\right)=\sum_{j=1, i=1}^{g} \frac{y_{j}}{F^{\prime}\left(x_{j}\right)} \frac{\partial}{\partial x_{j}} \frac{2 y_{i}}{F^{\prime}\left(x_{i}\right)\left(x_{i}-b_{r}\right)}, \tag{3.11}
\end{equation*}
$$

and express it by a lower derivative.

Here we shall summarize the derivatives of $F(x)$, which are shown by direct computations.

## Lemma 3.4.

(1) $\frac{\partial}{\partial x_{i}} F(x)=-\frac{F(x)}{x-x_{j}}$.
(2) $\left[\frac{\partial}{\partial x} F(x)\right]_{x=x_{i}}=\prod_{j \neq i}\left(x_{i}-x_{j}\right)$.
(3) $\frac{\partial}{\partial x_{k}} F^{\prime}\left(x_{k}\right)=\frac{1}{2}\left[\frac{\partial^{2}}{\partial x^{2}} F(x)\right]_{x=x_{k}}$.

In order to evaluate (3.11), we shall first show the next lemma.

## Lemma 3.5.

(1) $\quad \sum_{k=1}^{g} \frac{1}{F^{\prime}\left(x_{k}\right)}\left[\frac{\partial}{\partial x}\left(\frac{f(x)}{\left(x-b_{r}\right) F^{\prime}(x)}\right)\right]_{x=x_{k}}=\lambda_{2 g}+b_{r}+2 \wp_{g g}$.
(2)

$$
\begin{align*}
& \left(\sum_{k} \frac{y_{k}}{\left(x-x_{k}\right) F^{\prime}\left(x_{k}\right)}\right)^{2}=\sum_{k, l, k \neq l} \frac{2 y_{k} y_{l}}{\left(x-x_{k}\right)\left(x_{k}-x_{l}\right) F^{\prime}\left(x_{k}\right) F^{\prime}\left(x_{l}\right)}  \tag{3.15}\\
& \quad+\sum_{k} \frac{y_{k}^{2}}{\left(x-x_{k}\right)^{2} F^{\prime}\left(x_{k}\right)^{2}} \tag{3.16}
\end{align*}
$$

Proof. In order to prove (1), we shall consider an integral over a contour in $C_{g}$ and follow four steps as follows.
(1) Let $\partial C_{g}^{o}$ be a boundary of a polygon representation $C_{g}^{o}$ of the curve $C_{g}$,

$$
\begin{equation*}
\oint_{\partial C_{g}^{o}} \frac{f(x)}{\left(x-b_{r}\right) F(x)^{2}} \mathrm{~d} x=0 . \tag{3.17}
\end{equation*}
$$

(2) The divisor of the integrand of (1) is

$$
\begin{equation*}
\left(\frac{f(x)}{\left(x-b_{r}\right) F(x)^{2}} \mathrm{~d} x\right)=\sum_{i=1, b_{i} \neq b_{r}}^{2 g+1}\left(b_{i}, 0\right)-2 \sum_{i=1}^{g}\left(x_{i}, y_{i}\right)-2 \sum_{i=1}^{g}\left(x_{i},-y_{i}\right)-3 \infty . \tag{3.18}
\end{equation*}
$$

(3) Noting that the local parameter $t$ at $\infty$ is $x=1 / t^{2}$,

$$
\begin{equation*}
\operatorname{res}_{\infty} \frac{f(x)}{\left(x-b_{r}\right) F(x)^{2}} \mathrm{~d} x=-2\left(\lambda_{2 g}+b_{r}+2 \wp_{g g}\right) . \tag{3.19}
\end{equation*}
$$

(4) Noting that the local parameter $t$ at $\left(x_{k}, \pm y_{k}\right)$ is $t=x-x_{k}$,

$$
\begin{equation*}
\operatorname{res}_{\left(x_{k}, \pm y_{k}\right)} \frac{f(x)}{\left(x-b_{r}\right) F(x)^{2}} \mathrm{~d} x=\frac{1}{F^{\prime}\left(x_{k}\right)}\left[\frac{\partial}{\partial x}\left(\frac{f(x)}{\left(x-b_{r}\right) F^{\prime}(x)}\right)\right]_{x=x_{k}} . \tag{3.20}
\end{equation*}
$$

By arranging these, we obtain (3.15). On the other hand, (2) can be proved by using a trick: for $i \neq j$,

$$
\begin{equation*}
\frac{1}{\left(x_{j}-x_{i}\right)\left(x_{i}-b_{r}\right)}+\frac{1}{\left(x_{i}-x_{j}\right)\left(x_{j}-b_{r}\right)}=\frac{1}{\left(x_{j}-b_{r}\right)\left(x_{i}-b_{r}\right)} . \tag{3.21}
\end{equation*}
$$

Then we have (3.16).

Let us compute (3.11), which is $\sqrt{-1} \partial \mu^{(r)} / \partial u_{g}$, as follows:

$$
\begin{align*}
\frac{1}{2} \frac{\partial^{2}}{\partial u_{g}^{2}} \log F\left(b_{r}\right) & =2 \sum_{i=1}^{g} \frac{y_{i}}{F^{\prime}\left(x_{i}\right)} \frac{\partial}{\partial x_{i}} \frac{y_{i}}{F^{\prime}\left(x_{i}\right)\left(x_{i}-b_{r}\right)} \\
& +2 \sum_{i=1, j=1, j \neq i}^{g} \frac{y_{j}}{F^{\prime}\left(x_{j}\right)} \frac{\partial}{\partial x_{j}} \frac{y_{i}}{F^{\prime}\left(x_{i}\right)\left(x_{i}-b_{r}\right)} . \tag{3.22}
\end{align*}
$$

The first term in the right-hand side of (3.22) becomes

$$
\begin{align*}
& \sum_{i=1}^{g} \frac{y_{i}}{F^{\prime}\left(x_{i}\right)}\left(\frac{1}{y_{i} F^{\prime}\left(x_{i}\right)\left(x_{i}-b_{r}\right)} \frac{\mathrm{d} f\left(x_{i}\right)}{\mathrm{d} x_{i}}-\frac{y_{i}}{F^{\prime}\left(x_{i}\right)\left(x_{i}-b_{r}\right)}\left[\frac{\partial}{\partial x} F(x)\right]_{x=x_{i}}\right. \\
&\left.-\frac{2 y_{i}}{F^{\prime}\left(x_{i}\right)\left(x_{i}-b_{r}\right)^{2}}\right) . \tag{3.23}
\end{align*}
$$

Using the lemma 3.4 (1), it can be modified to
$\sum_{i=1, j=1, j \neq i}^{g} \frac{1}{F^{\prime}\left(x_{k}\right)}\left[\frac{\partial}{\partial x}\left(\frac{f(x)}{\left(x-b_{r}\right) F^{\prime}(x)}\right)\right]_{x=x_{i}}-\sum_{i=1}^{g} \frac{f\left(x_{i}\right)}{F^{\prime}\left(x_{i}\right)^{2}}\left(\frac{1}{\left(x_{i}-b_{r}\right)^{2}}\right)$.
Using (3.15), the first term in (3.24) is expressed well. On the other hand, the second term in the right-hand side of (3.22) is computed to

$$
\begin{equation*}
2 \sum_{i=1, j=1, j \neq i}^{g} \frac{y_{i} y_{j}}{F^{\prime}\left(x_{j}\right) F^{\prime}\left(x_{i}\right)} \frac{1}{\left(x_{j}-x_{i}\right)\left(x_{i}-b_{r}\right)} \tag{3.25}
\end{equation*}
$$

From lemma 3.5 (2), the second term in (3.24) and (3.25) becomes

$$
\begin{equation*}
\frac{1}{4}\left(\sum_{i=1}^{g} \frac{2 y_{i}}{F^{\prime}\left(x_{i}\right)} \frac{1}{\left(x_{i}-b_{r}\right)}\right)^{2} \equiv-\mu^{(r)^{2}} \tag{3.26}
\end{equation*}
$$

Hence we have theorem 3.2 (2).
Next we shall prove (3.3) as follows: from theorem 3.2 (2) ( $\gamma_{g-1} \equiv-\wp_{g g}$ due to (2.19) and (2.20)) we have

$$
\begin{equation*}
\frac{\partial}{\partial u_{g}} \mu^{(r)}=\frac{1}{\sqrt{-1}}\left(-2 \gamma_{g-1}+\lambda_{2 g}+b_{r}-\mu^{(r)^{2}}\right) \tag{3.27}
\end{equation*}
$$

We perform the differential in $u_{g}$ on both sides again,

$$
\begin{align*}
\frac{\partial^{2}}{\partial u_{g}^{2}} \mu^{(r)} & =\frac{1}{\sqrt{-1}} \frac{\partial}{\partial u_{g}}\left(-2 \gamma_{g-1}+\lambda_{2 g}+b_{r}-\mu^{(r)^{2}}\right) \\
& =\frac{1}{\sqrt{-1}}\left(-2 \sum_{i=1}^{g} \frac{2 y_{i}}{F^{\prime}\left(x_{i}\right)}-2 \mu^{(r)} \frac{\partial}{\partial u_{g}} \mu^{(r)}\right) \\
& =\frac{-2}{\sqrt{-1}}\left(\sum_{i=1}^{g} \frac{2 y_{i}}{F^{\prime}\left(x_{i}\right)}+\frac{1}{\sqrt{-1}} \mu^{(r)}\left[-2 \gamma_{g-1}+\lambda_{2 g}+b_{r}-\mu^{(r)^{2}}\right]\right) \tag{3.28}
\end{align*}
$$

In the second step, we used (3.27) again and

$$
\begin{equation*}
\frac{\partial}{\partial u_{g}} \gamma_{g-1}=-\sum_{i=1}^{g} \frac{2 y_{i}}{F^{\prime}\left(x_{i}\right)} . \tag{3.29}
\end{equation*}
$$

Noting $\chi_{i, g-1}=\gamma_{g-1}-x_{i}$, the first and second terms in the parenthesis are

$$
\begin{align*}
\sum_{i=1}^{g} \frac{2 y_{i}}{F^{\prime}\left(x_{i}\right)} & -\frac{2}{\sqrt{-1}} \gamma_{g-1} \mu^{(r)}=\sum_{i=1}^{g} \frac{2 y_{i}}{F^{\prime}\left(x_{i}\right)} \frac{x_{i}-b_{r}}{x_{i}-b_{r}}+\gamma_{g-1} \sum_{i=1}^{g} \frac{2 y_{i}}{F^{\prime}\left(x_{i}\right)\left(x_{i}-b_{r}\right)} \\
& =\frac{\partial}{\partial u_{g-1}} \log F\left(b_{r}\right)-\frac{2}{\sqrt{-1}} b_{r} \mu^{(r)} \tag{3.30}
\end{align*}
$$

Thus we obtain (3.7),

$$
\begin{equation*}
-\frac{1}{4} \frac{\partial^{3}}{\partial u_{g}^{3}} \phi^{(r)}=\left(\frac{\partial}{\partial u_{g-1}}-\left(\lambda_{2 g}+b_{r}\right) \frac{\partial}{\partial u_{g}}\right) \phi^{(r)}+\frac{1}{8}\left(\frac{\partial}{\partial u_{g}} \phi^{(r)}\right)^{3} . \tag{3.31}
\end{equation*}
$$

We differentiate (3.31) in $u_{g}$ again and then obtain (3.3). Hence we completely prove our theorem 3.2.

## 4. Discussion

We obtained the hyperelliptic solutions of the MKdV equation in terms of hyperelliptic alfunctions without any theta-functions, which is in contrast to the approach of Gesztesy and Holden [GH1] and others ([BBEIM] and references therein). For an arbitrary hyperelliptic curve, we can write down its explicit function form by the al-function. Miura transformation means a connection between the $\wp_{g g}$-functions and the $\mu^{(r)}$ in (3.2) which are differentials of the hyperelliptic al-functions; this aspect also differs from the study of the Miura transformation by Gesztesy and Holden [GH2].

According to [K12] and [D], Weierstrass found the $\sigma$ function for an elliptic curve, which he called the Al-function in honour of Abel, and his approach was to investigate divisor decomposition of a function,

$$
\begin{equation*}
y=4 y_{1} y_{2} y_{3}, \tag{4.1}
\end{equation*}
$$

for an elliptic curve $y^{2}=4 x^{3}+g_{3} x+g_{4}=4\left(x-e_{1}\right)\left(x-e_{2}\right)\left(x-e_{3}\right) ; y_{i}=\sqrt{x-e_{i}}$. These $y_{i}$ differ from his $\sigma$-function itself but correspond to our al-function (2.18). $y_{i}$ is expressed by a ratio of two $\sigma$ s. The functions $y_{i}$ are generators of Jacobi sn, cn and dn functions. Comparison of the $y_{i}$ with $\wp$ gives us fruitful information for the elliptic curve case. It is useful to identify these $s n$ with the $y_{i}$.

For the case of hyperelliptic curves, Weierstrass called the $y_{i}$ themselves al-functions and defined them as in (2.18) with explicit constant factor $\gamma^{\prime}[\mathrm{D}, \mathrm{K} 12, \mathrm{~W}]$. (The hyperelliptic sigma function is also a factor of the $\mathrm{al}_{r}$ as in (2.22), which was discovered by Klein [K11].) In [Ba3], Baker found the KdV hierarchy and KP equation around 1898 by comparing $F(x)$ and $\wp$. It is also important that we roughly identify with $F\left(b_{r}\right)$ and $\mathrm{al}_{r}$ and recognize that $\mu^{(r)}$ originates from $F\left(b_{r}\right)$. Miura transformation is a key to the relations between $F\left(b_{r}\right)$ and $\wp_{g g}$ as shown in this paper. In fact, the techniques in the proof of theorem 3.2 are essentially contained in [Ba3]. In other words we should regard a 'Miura transformation' as existing behind discoveries of the KdV hierarchy and KP equation by Baker, from [Ba3].

In the theory of elliptic functions, we know, by experience, that Jacobi elliptic functions rather than the $\wp$ function play important roles in physics, whereas $\wp$ is more essential in number theories and algebraic geometry. In fact, in the book [BF], there are many relations on Jacobi elliptic functions but not so many on $\wp$. Thus a question might arise of why there are such differences between Jacobi elliptic functions, special al-functions and the $\wp$ function. One of the answers is that the al-function is invariant for the affine transformation as mentioned in remark 3.3. On the other hand, $\wp$ is not. Of course for the standard representation of an elliptic curve, i.e. $y^{2}=4 x^{3}-g_{2} x+g_{3}$, in order to make the coefficient of $x^{2}$ vanish, the translation
freedom is constrained. However we can find $\wp$ even for $y^{2}=4 x^{3}+g_{1} x^{2}+g_{2} x+g_{3}$ and the nature of such a $\wp$ is $x$ itself in the affine space. Thus al and $\wp$ exist in different categories. As we show in [Ma2] and [Ma5], the al-function is associated with the differential geometry and solutions of Dirac equations, while $\wp$ is connected to algebraic geometry; $\wp$ is the affine coordinate of the curve.

Hence we conclude that Miura transformation is a connection between the worlds of $\wp$ and the al. I think that the researchers in the 19th century might have implicitly already recognized these facts. However as we can, now, look around both theories of 'Abelian functions', in the last century and the 19th century, I think that we should unify them and develop a new theory beyond them.

## Acknowledgments

I am grateful to Professor Y Ônishi for many suggestions for this work. I thank Professor V Z Enolskii for sending his interesting works and giving helpful comments. I also thank the referee for helpful suggestions.

## References

[Ba1] Baker H F 1897 Abelian Functions-Abel's Theorem and the Allied Theory Including the Theory of the Theta Functions (Cambridge: Cambridge University Press) (republished 1995)
[Ba2] Baker H F 1898 On the hyperelliptic sigma functions Am. J. Math. 20 301-84
[Ba3] Baker H F 1903 On a system of differential equations leading to periodic functions Acta Math. 27 135-56
[BBEIM] Belokolos E D, Bobenko A I, Enol'skii V Z, Its A R and Matveev V B 1994 Algebro-Geometric Approach to Nonlinear Integrable Equations (Berlin: Springer)
[BEL1] Buchstaber V M, Enolskii V Z and Leykin D V 1997 Hyperelliptic Kleinian functions and application Am. Math. Soc. Transl. 179 1-33
[BEL2] Buchstaber V M, Enolskii V Z and Leykin D V 1997 Kleinian functions, hyperelliptic Jacobians and applications Reviews in Mathematics and Mathematical Physics (London) (Gordon and Breach) pp 1-125
[BEL3] Buchstaber V M, Enolskii V Z and Leykin D V 2000 Uniformization of the Jacobi varieties of trigonal curves and nonlinear differential equations Funct. Anal. Appl. 34 1-15
[BF] Byrd P F and Friedman M D 1954 Handbook of Elliptic Integrals for Engineers and Physicists (Berlin: Springer)
[Bj] Björk J-E 1992 Analytic $\mathcal{D}$-Modules and Applications (Dordrecht: Kluwer)
[CEEK] Christiansen P L, Eilbeck J C, Enolskii V Z and Kostov N A 2000 Quasi-periodic and periodic solutions for coupled nonlinear Schrödinger equations of Manakov type Proc. R. Soc. A 456 2263-81
[D] Dieudonné J 1978 Abrég'e D'Histoire des Mathématiques vol 2 (Paris: Hermann)
[DKJM] Date E, Kashiwara M, Jimbo M and Miwa T 1983 Transformation groups for soliton equations Nonlinear Integrable Systems-Classical Theory and Quantum Theory ed M Jimbo and T Miwa (Singapore: World Scientific) pp 39-119
[EE] Eilbeck J C and Enolskii V Z 2000 Bilinear operators and the power series for the Weierstrass $\sigma$ function J. Phys. A: Math. Gen. 33 791-4
[EEK] Eilbeck J C, Enolskii V Z and Kostov N A 2000 Quasi-periodic and periodic solutions for vector nonlinear Schrödinger equations J. Math. Phys. 41 8236-48
[EEL] Eilbeck J C, Enolskii V Z and Leykin D V 2000 On the Kleinian construction of Abelian functions of canonical algebraic curves Proc. Conf. SIDE III: Symmetries of Integrable Difference Equations (Saubadia, 1998) (CRM Proc. Lecture Notes) pp 121-38
[EEP] Eilbeck J C, Enolskii V Z and Previato E 2001 Varieties of elliptic solitons J. Phys. A: Math. Gen. 34 2215-27
[G] Grant D 1990 Formal groups in genus two J. Reine Angew. Math. 411 96-121
[GGKM] Gradner C S M, Greene J M, Kruska M D and Miura R M 1967 Method for solving the Korteweg-de Vries equation Phys. Rev. Lett. 19 1095-7
[GH1] Gesztesy F and Holden H 2000 A combined sine-Gordon and modified Korteweg-de Vries hierarchy and its algebro-geometric solutions Preprint solv-int/9707010 pp 133-73
[GH2] Gesztesy F and Holden H 1998 The Cole-Hopf and Miura transformation revised Preprint solv-int/9812025
[K11] Klein F 1886 Ueber hyperelliptische sigmafunctionen Math. Ann. 27 431-64
[K12] Klein F 1926 Vorlesungen über die Entwicklung derMathematik im 19 Jahrhundert I (Berlin: Springer)
[Kr] Krichever I M 1977 Methods of algebraic geometry in the theory of nonlinear equations Russ. Math. Surv. 32 185-213
[L] Lamb G L Jr 1980 Elements of Soliton Theory (New York: Wiley-Interscience)
[Mac] Macdonald I G 1995 Symmetric Functions and Hall Polynomials 2nd edn (Oxford: Clarendon)
[Ma1] Matsutani S 1998 Statistical mechanics of elastica on plane: origin of MKdV hierarchy J. Phys. A: Math. Gen. 199831 2705-25
[Ma2] Matsutani S 2001 Closed loop solitons and sigma functions: classical and quantized elasticas with genera one and two J. Geom. Phys. 39 50-61
[Ma3] Matsutani S 2001 Hyperelliptic solutions of KdV and KP equations: reevaluation of Baker's study on hyperelliptic sigma functions J. Phys. A: Math. Gen. 34 4721-32
[Ma4] Matsutani S 2001 Soliton solutions of Korteweg-de Vries equations and hyperelliptic sigma functions Preprint math-ph/0105032
[Ma5] Matsutani S 2001 Hyperelliptic loop solitons with genus $g$ : investigations of a quantized elastica J. Geom. Phys. (nlin.SI/0108002)
[MT] McKean H P and Trubowitz 1976 Hill's operator and hyperelliptic function theory in the presence of infinitely many branch points Commun. Pure Appl. Math. 29 143-226
[N] Nijhoff F W 2000 Discrete Dubrovin equations and separation of variables for discrete systems Chaos Solitons Fractals 11 19-28
[Ô1] Ônishi Y 1998 Complex multiplication formulae for curves of genus three Tokyo J. Math. 21 381-431
[Ô2] Ônishi Y 2002 Determinant expressions for Abelian functions in genus two Glasgow Math. J. (math.NT/0105189)
[SN] Sato M and Noumi M 1984 Soliton equations and infinite-dimensional Grassmann manifold Sofia University Lecture Note 18 (Tokyo) (in Japanese)
[SS] Sato M and Sato Y 1984 Nonlinear Partial Differential Equations in Applied Science ed H Fujita, P D Lax and G Strang (Tokyo: Kinokuniya)
[TD] Tanaka S and Date E 1979 KdV Houteishiki [KdV Equation] (Tokyo: Kinokuniya) (in Japanese)
[W] Weierstrass K 1894 Mathematische Werke I (Berlin: Mayer and Müller)
[Z] Zamolodchikov Al B 1994 Painlevé III and 2D polymers Nucl. Phys. B 432 [FS] 427-56

